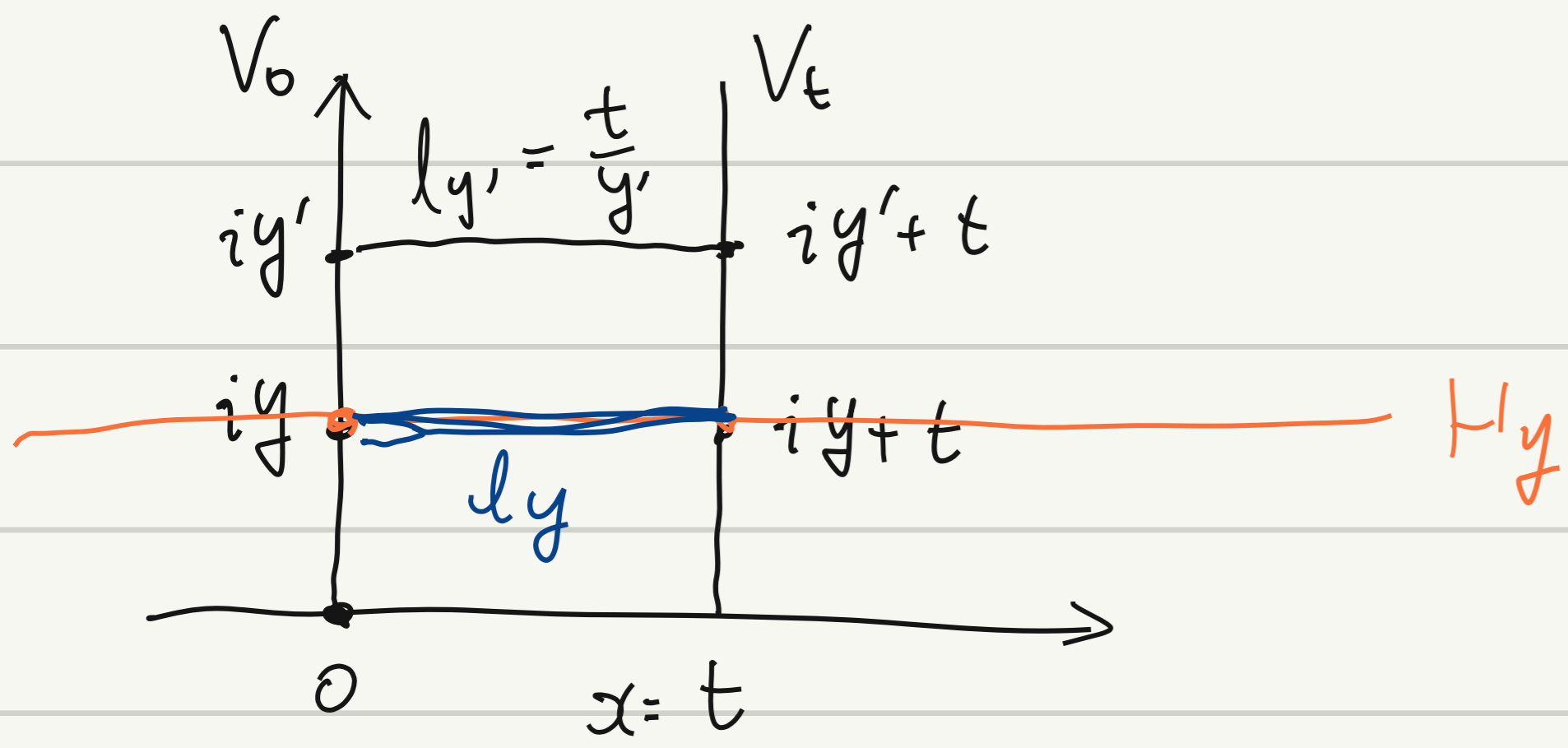


2.

$$T_t: \mathbb{H}^1 \rightarrow \mathbb{H}^1$$

$$z \mapsto z+t$$



a) $x = t$

b) $dy = d_{\mathbb{H}^1}(\gamma) = \int_0^t \frac{1}{y} dt = \frac{t}{y}$

$$\gamma: [0, t] \mapsto \mathbb{H}^1$$

$$s \mapsto iy + s$$

$$\dot{\gamma}(s) = (1, 0)$$

$$\|\dot{\gamma}(s)\|_{\mathbb{H}^1} = \frac{\|\dot{\gamma}(s)\|_{\mathbb{E}}}{|\operatorname{Im} \gamma(s)|} = \frac{1}{y}$$

c) $\lim_{y \rightarrow +\infty} dy = \lim_{y \rightarrow +\infty} \frac{t}{y} = 0$

$$l(f) := \inf \{ d_{\mathbb{H}^1}(z, f(z)) \mid z \in \mathbb{H}^1 \}$$

$z \in \mathbb{H}^1$ realizes $l(f)$

if $d_{\mathbb{H}^1}(z, f(z)) = l(f)$

d) $d_{\mathbb{H}^1}(iy, T_t(iy)) < \frac{t}{y} \rightarrow 0$
 $y \rightarrow +\infty$

$$\Rightarrow \inf \{ d_{\mathbb{H}^1}(z, T_t(z)) \mid z \in \mathbb{H}^1 \}$$

$$\leq \inf \{ d_{\mathbb{H}^1}(iy, T_t(iy)) \mid y \in \mathbb{R} \}$$

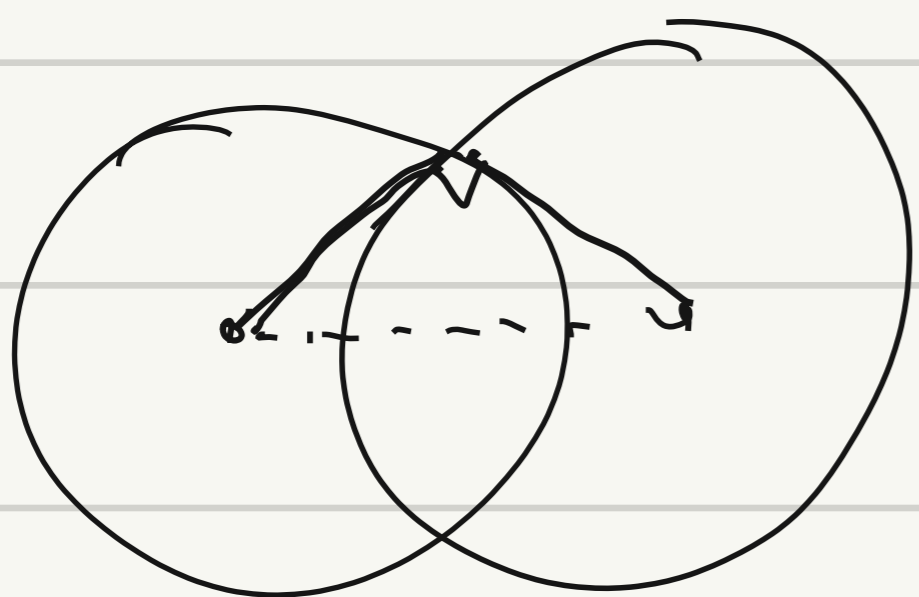
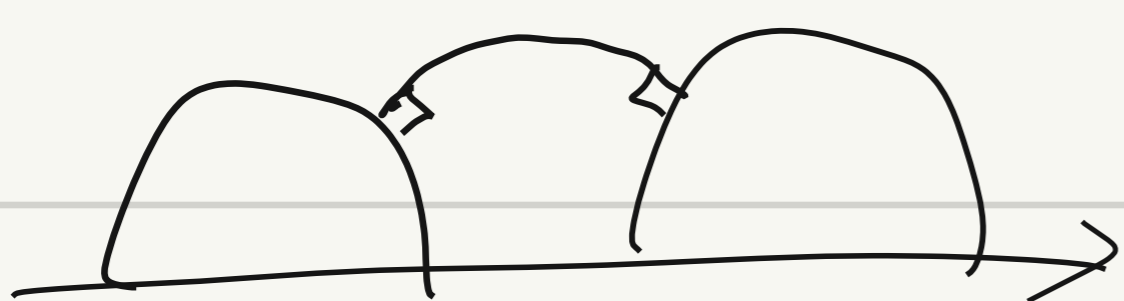
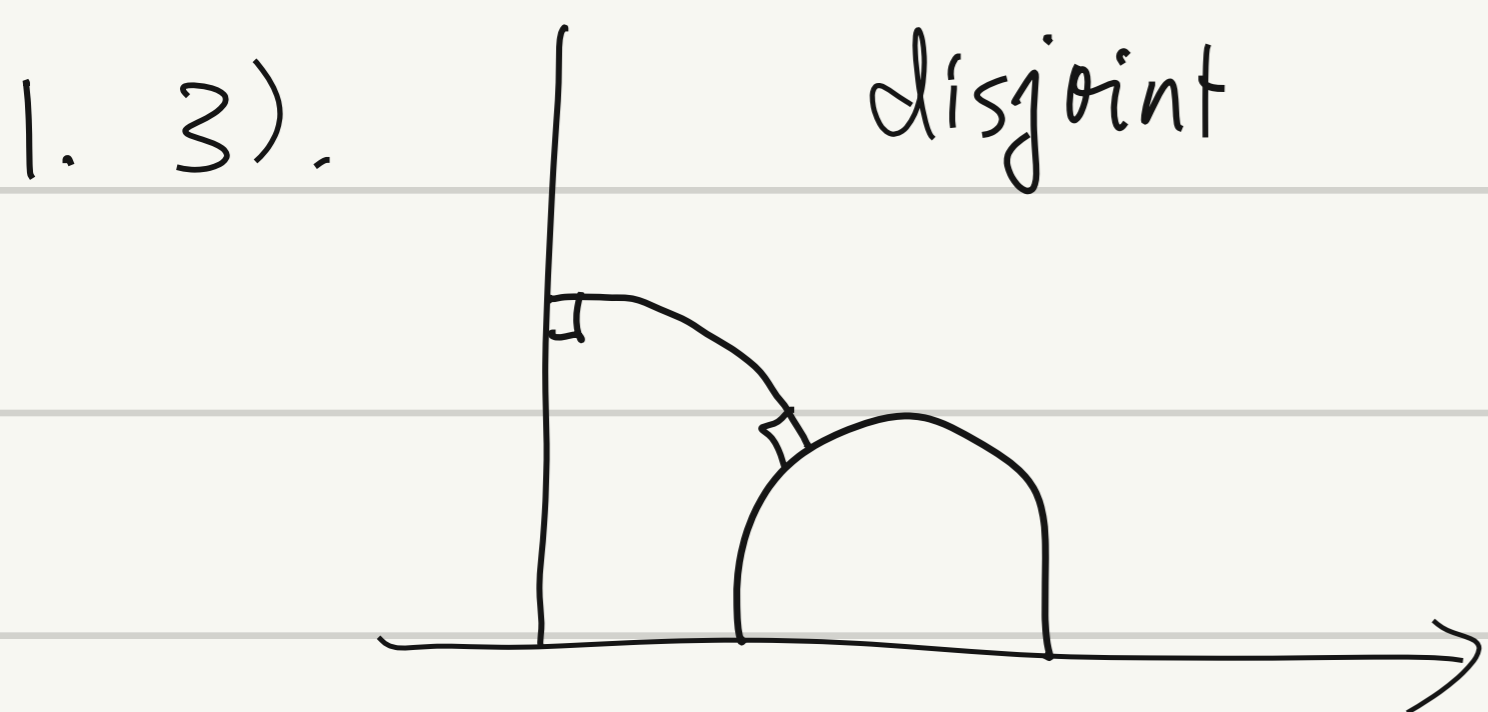
$$= 0$$

$$\Rightarrow l(T_t) = 0$$

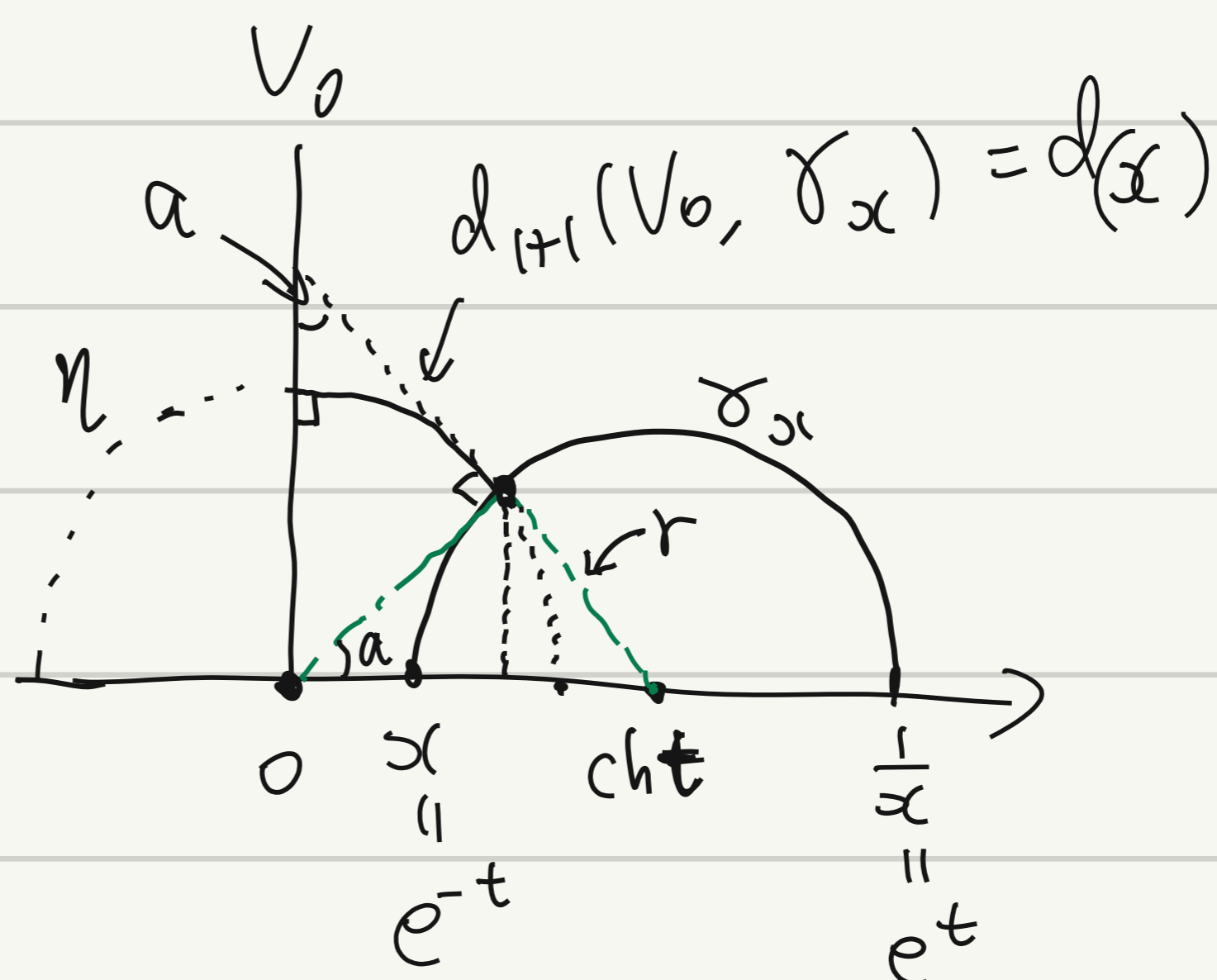
$$\forall z \quad T_t(z) = z+t \neq z$$

$$\Rightarrow d_{\mathbb{H}^1}(z, T_t(z)) > 0$$

$$\Rightarrow \nexists z \text{ realize } l(T_t)$$



$$\log \operatorname{tg} \frac{b}{2} - \log \operatorname{tg} \frac{a}{2}$$



$$x = e^{-t}$$

$$r = \frac{\frac{1}{x} - x}{2}$$

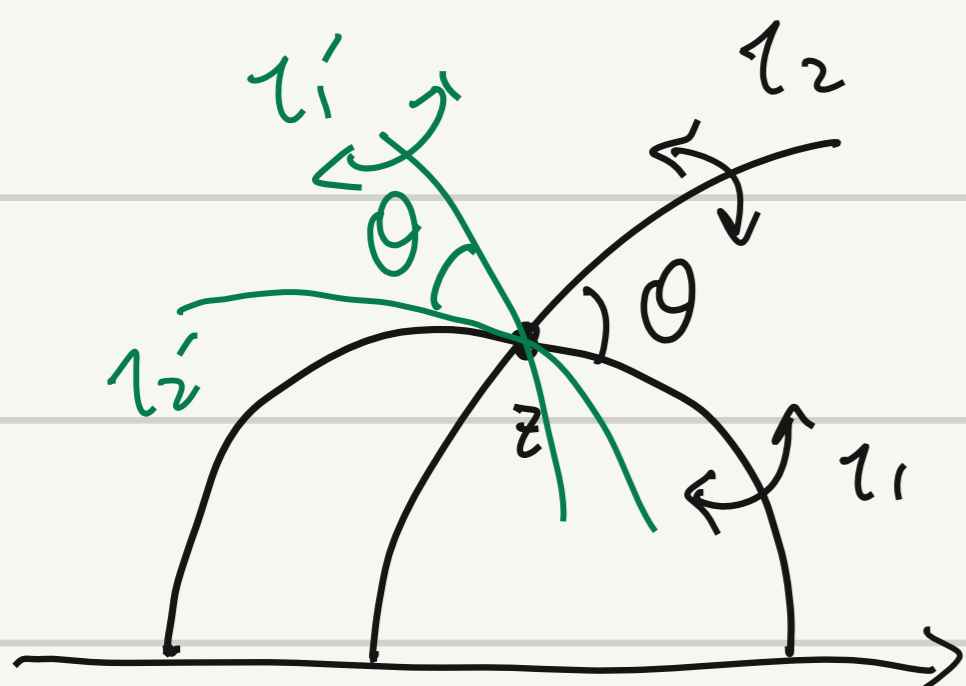
$$= \operatorname{sh} t$$

$\eta \perp V_0 \Rightarrow$ Euclidean center of $\eta = 0$

$\sigma_x \perp \eta \Rightarrow$

$$d_x = \log \operatorname{tg} \frac{\pi}{2} - \log \operatorname{tg} \frac{a}{2}$$

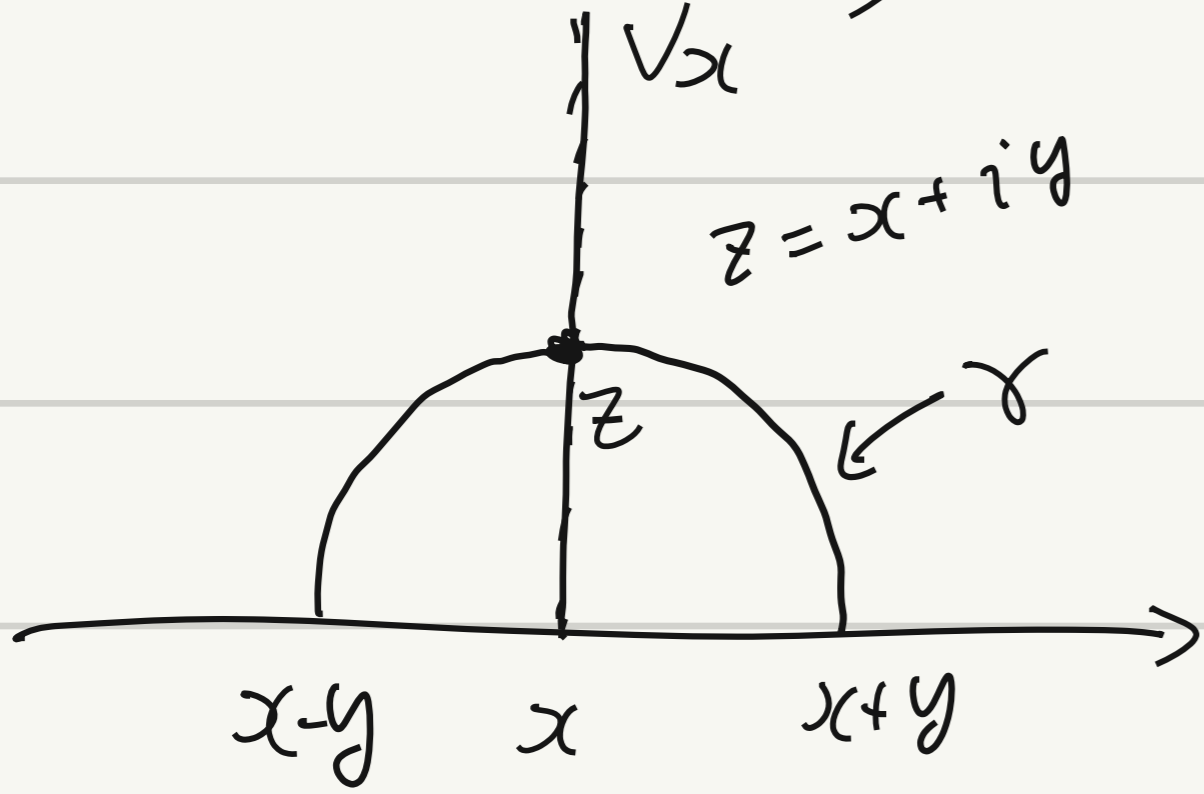
$$= \log \frac{\cos a + 1}{\sin a}$$



$$l_2' \circ l_1' = l_2 \circ l_1 = \rho_{\theta} \quad 2\theta\text{-rotation.}$$

$$\uparrow 2\theta = \pi$$

$$\theta = \frac{\pi}{2}$$



$$\gamma = C(x, y)$$

$$\gamma(w) = \frac{x\bar{w} + y^2 - x^2}{\bar{w} - x}$$

$$\gamma_x(w) = -\bar{w} + 2x$$

$$\begin{aligned} \gamma \circ \gamma_x(w) &= \frac{x(-\bar{w} + 2x) + y^2 - x^2}{(-\bar{w} + 2x) - x} = \frac{-x\bar{w} + 2x^2 + y^2 - x^2}{-\bar{w} + x} \\ &= \frac{-x\bar{w} + y^2 + x^2}{-\bar{w} + x} \end{aligned}$$