### PROBLEM SET

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### 1. BASIC RIEMANNIAN GEOMETRY

**Exercise 1.1.** Let  $\gamma(t) = (t, y(t)), t \in [0, 1]$  be the curve defined by

$$y(t) = \begin{cases} t \cos(\frac{\pi}{2t}), & t \neq 0, \\ 0, & t = 0. \end{cases}$$
(1.1)

Show that  $\gamma$  is non-rectifiable.

**Exercise 1.2.** Let g be a Riemannian structure on U. Show that  $d_g: U \times U \to [0, \infty)$  gives a metric structure on U such that (U, g) becomes a metric space.

**Exercise 1.3.** Show that any geodesic in  $\mathbb{R}^n$  is a line segment. Then prove that  $(\mathbb{R}^n, d_0)$  is a length space. Under what condition of U is the space  $(U, d_0)$  a length space?

Recall the definition of covariant derivative along a curve  $\gamma$ .

**Definition 1.4** (Covariant derivative). For any smooth map  $\Gamma : U \to (\mathbb{R}^n)^* \otimes (\mathbb{R}^n)^*$  that maps every  $x \in U$  to a bilinear map  $\Gamma_x : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n$ , the corresponding covariant derivative X along  $\gamma$  is defined by

$$\nabla_{\gamma} X = \frac{d}{dt} X(t) + \Gamma_{\gamma(t)}(\gamma'(t), X).$$
(1.2)

**Exercise 1.5.** In (1.2), assume that  $\Gamma$  is chosen such that  $\Gamma_x(u, v) \equiv \frac{1}{2}G_x^{-1}DG_x(u)v$  for any  $x \in U$ . Let X, Y be C<sup>1</sup>-vector fields along  $\gamma$  and let  $f : U \to \mathbb{R}$  be any C<sup>1</sup>-function. Show that

(1)  $\nabla_{\gamma}(\alpha X + \beta Y) = \alpha \nabla_{\gamma} X + \beta \nabla_{\gamma} Y$ ,

(2) 
$$\nabla_{\gamma}(fX) = f' \cdot X + f \nabla_{\gamma} X$$
,

(3)  $\frac{d}{dt}g_{\gamma}(X,Y) = g_{\gamma}(\nabla_{\gamma}X,Y) + (X,\nabla_{\gamma}Y).$ 

**Exercise 1.6.** In geodesic normal coordinates centered at  $p \in U$ , we denote

$$g_{ij} \equiv g(\partial_i, \partial_j), \quad \nabla_{\partial_i} \partial_j = \Gamma^k_{ij} \partial_k.$$
 (1.3)

Show that  $g_{ij}(p) = \delta_{ij}$ ,  $\Gamma^k_{ij}(p) = 0$ .

**Exercise 1.7.** We define  $\mathscr{R}(X,Y)Z \equiv \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]}Z$  for  $X, Y, Z \in \mathfrak{X}(U)$ . Show that  $\mathscr{R}$  is tensorial and  $R = \mathscr{R}$ .

**Exercise 1.8.** Let  $\{x_i\}_{i=1}^n$  be the geodesic normal coordinate system at  $p \in U$ . Let  $\gamma : [0,1] \to U$  be a geodesic with  $\gamma(0) = p$  and  $\gamma'(0) = \sigma$ . Prove the following Taylor expansions: (1) Let J(t) be a Jacobi field along  $\gamma$  with J(0) = 0 and J'(0) = v. Then

$$||J(t)||^{2} = t^{2} - \frac{1}{3}\sec_{p}(\sigma, v) \cdot t^{4} + O(t^{5}).$$
(1.4)

(2) Let  $G \equiv \det(g_{ij})$ . Then

$$\sqrt{G} = 1 - \frac{1}{6} \operatorname{Ric}_{ij}(p) x_i x_j + O(|x|^3).$$
(1.5)

(3) Let  $B_r(p) \equiv \{x \in U | d_g(x, p) \le p\}$ . Then

$$\frac{\operatorname{Vol}(B_r(p))}{\omega_n r^n} = 1 - \frac{\operatorname{Sc}(p)}{6(n+2)}r^2 + O(r^3).$$
(1.6)

(4) Let  $S_r(p) \equiv \partial B_r(p)$ . Then

$$\frac{\operatorname{Area}(S_r(p))}{n\omega_n r^{n-1}} = 1 - \frac{\operatorname{Sc}(p)}{6}r^2 + O(r^3).$$
(1.7)

**Exercise 1.9.** Consider the following warped product metrics on the 2-disc  $\mathbb{D} \subset \mathbb{R}^2$ :

$$g_{+} = dr^{2} + \sin^{2}(r) \cdot d\theta^{2},$$
 (1.8)

$$g_{-} = dr^2 + \sinh^2(r) \cdot d\theta^2. \tag{1.9}$$

Prove that  $\sec_{g_+} \equiv 1$  and  $\sec_{g_-} \equiv -1$ .

# 2. Geometry of Riemannian manifolds

**Exercise 2.1.** Let  $\gamma : [0,1] \to U$  be a curve. Let  $\nabla$  be a linear connection on U. A vector field X is said to be parallel along  $\gamma$  if  $\nabla_{\gamma'(t)}X(t) \equiv 0$  for any  $t \in [0,1]$ . Prove that for any  $v \in T_{\gamma(0)}U$ , there exists a unique parallel vector field X along  $\gamma$  with X(0) = v.

**Exercise 2.2.** Let  $\nabla$  be the Levi-Civita connection on (U,g). Prove the following Koszul formula

$$2g(\nabla_X Y, Z) = X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) + g([X, Y], Z) + g([Z, X], Y) - g([Y, Z], X).$$
(2.1)

**Exercise 2.3.** Let  $M^n$  be a differentiable n-manifold. Then  $\dim(T_pM^n) = n$  for any  $p \in M^n$ .

**Exercise 2.4.** Let  $(\mathbb{T}^2 = \mathbb{R}^2/\mathbb{Z}_2, g_{flat})$  be a flat torus. Write a geodesic  $\gamma \subset \mathbb{T}^2$  which is dense  $\mathbb{T}^2$ .

**Exercise 2.5.** Let  $\varphi : (U, g_0) \to (\varphi(U), g_0)$  be an isometry. Show that there exists an isometry  $\overline{\varphi}$  on  $\mathbb{R}^n$  such that  $\varphi = \overline{\varphi}|_U$ .

**Exercise 2.6.** Show that  $\Delta(fg) = f\Delta g + g\Delta f + 2g(\nabla f, \nabla g)$ .

**Exercise 2.7.** Let  $(M^n, g)$  and  $(N^k, h)$  be Riemannian manifolds. Then the Levi-Civita connection  $\nabla$  of  $(M^n \times N^k, g \oplus h)$  satisfies

$$\nabla_{Y_1+Y_2}(X_1+X_2) = \nabla_{Y_1}^g X_1 + \nabla_{Y_2}^h X_2, \quad X_i+Y_i \in TM^n \oplus TN^k, \ i = 1, 2.$$
(2.2)

In particular,  $\gamma(t) = (\gamma_1(t), \gamma_2(t))$  is a geodesic if  $\gamma_1$  and  $\gamma_2$  are geodesics on  $M^n$  and  $N^k$ , respectively.

**Exercise 2.8.** Let  $p = (x_1, y_1)$  and  $q = (x_2, y_2)$  be any points on the product manifold  $(M^n \times N^k, g \oplus h)$ . Then

$$d_{g\oplus h}^2(p,q) = d_g^2(x_1, x_2) + d_h^2(y_1, y_2).$$
(2.3)

**Exercise 2.9.** Let  $(M^n, g)$  be a Riemannian manifold. Show that for any r > 0,  $Sc_{\bar{g}_r} =$  $r^{-2} \operatorname{Sc}_{a_r}$ . Then establish the similar rescaling relation for sectional and Ricci curvatures.

**Exercise 2.10.** Consider the Euclidean metric  $g_0$  on  $\mathbb{R}^{n+1}$  in polar coordinates  $g_0 = dr^2 + dr^2$  $r^2 q_{\mathbb{S}^n}$ . Prove that  $\sec_{\mathbb{S}^n} \equiv +1$ .

**Exercise 2.11.** Let  $\eta : \underbrace{TM \times \ldots \times TM}_{r} \to C^{\infty}(M^{n})$  be a tensor multilinear map on  $M^{n}$ , called a (0, r)-tensor field. Let  $X \in \mathfrak{X}(M^n)$ . We define

$$\mathfrak{L}_X \eta(Y_1, \dots, Y_r) \equiv X(\eta(Y_1, \dots, Y_r)) - \sum_{i=1}^r \eta(X_1, \dots, [X, Y_i], \dots, X_r).$$
(2.4)

**Exercise 2.12.** Let  $\eta$  and  $\zeta$  be (0,r) and (0,s) tensor fields on  $M^n$ , repsectively. For any  $X \in \mathfrak{X}(M^n)$ , show that

$$\mathfrak{L}_X(T \otimes S) = (\mathfrak{L}_X T) \otimes S + T \otimes (\mathfrak{L}_X S).$$
(2.5)

As a special case,  $\mathfrak{L}_X(fT) = X(f) + f\mathfrak{L}_XT$  for any  $f \in C^{\infty}(M^n)$ .

**Exercise 2.13.** Prove that in the above warped product metric,  $2 \operatorname{Hess}(r) = \mathfrak{L}_{\partial_r}g$  and  $\operatorname{Hess}(r) = (f \cdot \partial_r f)h.$ 

**Exercise 2.14.** Let  $(r, x_1, \ldots, x_{n-1})$  be local coordinates on  $(a, b) \times N^{n-1}$ . Prove the following curvature identities for the warped product metric  $dr^2 + f^2(r)h$ :

- (1)  $R^g_{ijk\ell} = f^2(r)R^h_{ijk\ell} + f^2(r)(f'(r))^2(h_{ik}h_{j\ell} h_{i\ell}h_{jk}).$ (2)  $R^g_{ij\ell r} = 0$  and  $R^g_{rijr} = -f(r) \cdot f''(r)g_{ij}.$
- (3)  $\operatorname{sec}_g(\partial_i, \partial_j) = f^{-2}(r)(\operatorname{sec}_h(\partial_i, \partial_j) (f'(r))^2)$  and  $\operatorname{sec}_g(\partial_r, \partial_i) = -f^{-1}(r)f''(r)$ .
- (4)  $\operatorname{Ric}_{ij}^{g} = \operatorname{Ric}_{ij}^{h} \left( (n-2)(f'(r))^{2} + f(r)f''(r) \right) g_{ij}.$
- (5)  $\operatorname{Ric}_{ir}^{g} = 0$  and  $\operatorname{Ric}_{rr}^{g} = -(n-1)f^{-1}(r)f''(r)$ .

#### 3. More examples of Riemannian structures

**Exercise 3.1.** Let  $g_C = dr^2 + r^2 \cdot h$  be the cone metric of  $C(\Sigma)$ . Show that  $\mathfrak{L}_{\partial_r}g = \frac{2}{r}g$ .

**Exercise 3.2.** Prove that a metric cone  $C(\Sigma)$  is smooth everywhere if and only if  $C(\Sigma)$  is flat which is equivalent to say the cross-section  $\Sigma$  is isometric to the round sphere of curvature +1.

**Exercise 3.3.** Let  $(C(\Sigma), g_C, z_*)$  be a metric cone over a compact manifold  $(\Sigma, h)$ , where  $z_*$ is the cone tip. Prove that away from the cone tip  $z_*$ ,  $\operatorname{Ric}_{q_C} \equiv 0$  iff  $\operatorname{Ric}_h \equiv (n-2)h$ , and  $g_C$ is flat iff  $\operatorname{sec}_h \equiv +1$ .

**Exercise 3.4.** Let  $Z \equiv \text{Susp}_k(\Sigma)$  with  $k \in \{-1, 1\}$ . Show that  $\sec_{\Sigma} \equiv 1$  if and only if  $\sec_{Z} \equiv k$ .

**Exercise 3.5.** Let  $M^n$  be a differentiable manifold. Show that for any  $X, Y, Z \in \mathfrak{X}(M^n)$ , we have the following identities:

(1) [Y, X] = -[X, Y].(2) [[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0.

As a result,  $\mathfrak{X}(M^n)$  is a Lie algebra (of infinite dimension).

**Exercise 3.6** (An alternative definition of Lie derivative). Let R be a (0,r) tensor field on  $M^n$ . Let X be a vector field with a flow  $\phi_t$ . Then we define

$$(\mathfrak{L}_X \mathcal{R})_p(v_1, \dots, v_r) = \frac{d}{dt} \Big|_{t=0} (\phi_t^* \mathcal{R}_p(v_1, \dots, v_r)),$$
(3.1)

where  $\phi_t^* \mathcal{R}(v_1, \ldots, v_r) \equiv \mathcal{R}(D\phi_t(v_1), \ldots, D\phi_t(v_r))$  and  $v_1, \ldots, v_r \in T_p M^n$ . Show that this definition coincides with the previous one involving the Lie bracket.

**Exercise 3.7.** Let  $X \in \mathfrak{X}(M)$ . Show that  $\mathfrak{L}_X g = 0$  if and only if the flow of X is an isometric action.

## 4. The space of metric structures

**Exercise 4.1.** Show that the tangent cone at any point in Riemannian n-manifold is isometric to  $\mathbb{R}^n$ .

**Exercise 4.2.** Let  $(\Sigma, h)$  be any closed Riemannian manifold with  $\operatorname{diam}_h(\Sigma) \leq \pi$ . Let  $(C(\Sigma), d_C)$  be the metric cone over  $\Sigma$  with a vertex  $z_*$ . Show that the tangent cone of  $C(\Sigma)$  at  $p \neq z_*$  is isometric to  $\mathbb{R}^n$ , and the tangent cone of  $C(\Sigma)$  at  $z_*$  is isometric to itself.

**Exercise 4.3.** Let  $(\Sigma, h)$  be any closed Riemannian manifold with  $\operatorname{diam}_h(\Sigma) \leq \pi$ . Let  $(\operatorname{Susp}_{+1}(\Sigma), d_C)$  be the spherical suspension over  $\Sigma$  with vertices  $z_*$  and  $w_*$ . Show that the tangent cone of  $\operatorname{Susp}_{+1}(\Sigma)$  at any vertex is a metric cone.

**Exercise 4.4.** Show that the asymptotic cone of a complete non-compact metric space (X, d) is independent of the choice of the reference point p.

**Exercise 4.5.** Let (X, d) be a compact metric space. Show that for any  $\epsilon > 0$ , there is a finite  $\epsilon$ -net  $X(\epsilon) \subset X$ .

**Exercise 4.6.** Read Chapter 5 of Petersen's textbook. Understand the concepts: conjugate point, injectivity radius, and segment domain.