

# Introduction to hyperbolic surfaces

## Exercises IV

For  $\theta \in [0, 2\pi)$ ,  $\lambda > 0$  and  $t \in \mathbb{R}$ , we consider

$$K_\theta = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}, \quad A_\lambda = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda^{-1} \end{bmatrix} \quad \text{and} \quad N_t = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}.$$

Their corresponding Möbius transformations are  $\rho_\theta$ ,  $\phi_\lambda$  and  $T_t$  respectively. Recall that Möbius transformations on  $\mathbb{H}$  are orientation preserving isometries of  $\mathbb{H}$ .

Let  $B$  and  $C$  be matrices in  $\text{SL}(2, \mathbb{R})$ . Recall that  $B$  and  $C$  are *similar* to each other in  $\text{SL}(2, \mathbb{R})$  if there is a matrix  $P \in \text{SL}(2, \mathbb{R})$ , such that  $B = PCP^{-1}$ , (i.e.  $B$  can be obtained by taking the conjugation of  $C$  by  $P$ ). In the following, by being similar, we always mean being similar in  $\text{SL}(2, \mathbb{R})$ .

1. Show that for any matrices  $B$  and  $C$  in  $\text{SL}(2, \mathbb{R})$ , we have

$$\text{(Easy)} \quad \text{tr } B = \text{tr } B^{-1}$$

$$\text{(Normal)} \quad \text{tr } B \text{tr } C = \text{tr } BC + \text{tr } BC^{-1}$$

(Hint: Traces of matrices are invariant under conjugation.)

2. Let  $M \in \text{SL}(2, \mathbb{R})$ . We would like to check if  $M$  and  $M^{-1}$  are similar to each other in a geometric way.

- a) (Easy) Show that for any geodesic, there is a Möbius transformation exchanging its two end points.

(Hint: Ex III 3)

- b) (Normal) Use a) to show that any matrix  $M$  associated to a hyperbolic Möbius transformation is similar to its inverse  $M^{-1}$ .

(Hint: Use a) on the axis of  $M$  to find a Möbius transformation, and consider its associated matrix.)

- c) (Hard) The orientation on  $\mathbb{H}$  induces an orientation on each cycle and each horocycle (described by giving a positive rotation direction). Moreover this orientation on a cycle or a horocycle is preserved by orientation preserving isometries. Use this fact to show that

- i. If  $M = N_t$ , then  $M$  is similar to  $M^{-1}$ , if and only if  $t = 0$ .

- ii. If  $M = K_\theta$ , then  $M$  is similar to  $M^{-1}$ , if and only if  $\theta \in \{0, \pi/2, \pi, 3\pi/2\}$ .

(Hint: Understand (i) the difference between the isometries of  $\mathbb{H}$  induced by  $M$  and  $M^{-1}$ , and (ii) the geometric meaning of taking conjugation)

3. We consider the matrix

$$M = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}.$$

Let  $f$  be the Möbius transformation associated to  $M$ . We would like to use hyperbolic geometry to find  $J(M)$  the Jordan normal form of  $M$ .

- a) (Easy) Use the trace to show that  $M$  is hyperbolic.
  - b) (Normal) Compute its eigenvalues  $\mu$  and  $\mu^{-1}$  with  $\mu > 1$ .
  - c) (Normal) Find the fixed points  $x_1$  and  $x_2$  of  $f$  with  $x_1 < x_2$ .
  - d) (Easy) Find the parabolic isometry  $T_t$ , such that  $T_t(x_1) = -T_t(x_2)$ , and write down the matrix corresponding  $N_t$ .
  - e) (Hard) Find an elliptic isometry sending  $T_t(x_1)$  to 0 and  $T_t(x_2)$  to  $\infty$ , and write down its matrix  $B$ .
- (Hint: Try to get the rotation around  $iy$  for an angle  $\theta$  from the rotation around  $i$  for an angle  $\theta$ )
- f) (Easy) Compute  $P = BN_t$  and verify that  $P$  satisfies:

$$PMP^{-1} = J(M).$$

- g) (Easy) Compare  $J(M)$  with  $A_\mu$ .
- h) (Easy) Let  $P_\lambda = A_\lambda P$ . Show that for any  $\lambda > 0$ , we have

$$P_\lambda MP_\lambda^{-1} = J(M).$$

4. We consider the following 3 subgroups of  $\mathrm{SL}(2, \mathbb{R})$ :

$$\begin{aligned} K &= \{K_\theta \mid \theta \in [0, 2\pi)\}, \\ A &= \{A_\lambda \mid \lambda > 0\}, \\ N &= \{N_t \mid t \in \mathbb{R}\}. \end{aligned}$$

The KAN decomposition (also called Iwasawa decomposition) of  $\mathrm{SL}(2, \mathbb{R})$  states that: every  $M \in \mathrm{SL}(2, \mathbb{R})$  can be written as a product  $K_\theta A_\lambda N_t$  in a unique way (i.e.  $\theta$ ,  $\lambda$  and  $t$  are unique).

We would like to show this in a geometric way.

- a) (Normal) By considering the algorithm that used for determining an isometry, show that for any matrix  $M \in \mathrm{SL}(2, \mathbb{R})$  with  $\mathrm{tr} M \geq 0$ , we can find matrices  $K_\theta$ ,  $A_\lambda$  and  $N_t$ , such that  $M = K_\theta A_\lambda N_t$ , for some  $\theta \in [0, \pi)$ ,  $\lambda > 0$  and  $t \in \mathbb{R}$ .
- b) (Easy) Show that  $K_\pi = -Id$ . (Hence the associated Möbius transformation is the identity map.)
- c) (Normal) Show that for any  $\theta \in [0, 2\pi)$  and  $t \in \mathbb{R}$ . If  $K_\theta N_t$  preserves the vertical geodesic  $V_0$ , then we have  $\theta = 0, \pi/2$  or  $\pi$  and  $t = 0$ .  
(Hint: Check if it preserves the end points up to exchange them.)
- d) (Normal) Use c) to conclude that if  $K_\theta A_\lambda N_t = A_\mu$ , where  $\theta \in [0, 2\pi)$ ,  $\lambda > 0$ ,  $\mu > 0$  and  $t \in \mathbb{R}$ , then we have  $\theta = 0$ ,  $\lambda = \mu$  and  $t = 0$ .  
(Hint: A necessary condition for being equal is that they preserve the same axis without exchanging the end points (i.e. the orientation on the axis).)
- e) (Easy) Conclude that the KAN decomposition for any  $M \in \mathrm{SL}(2, \mathbb{R})$  is unique.  
(Hint:  $K$  and  $N$  are subgroups of  $\mathrm{SL}(2, \mathbb{R})$ , hence are closed under multiplication.)